

ADW-BW Twelve Component Batch Weighing Controller

A Supplement to be read in conjunction with the ADW15 User Manual

User Manual mantracourt.com



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ADW-BW 12 Component Batch Weigher

Designed around the highly successful Mantraweigh ADW15, Strain gauge Amplifier/Controller, and Remote Multi Set Point system; The ADW-BW Batch Weigher special software program, makes provision for the weighing and mixing of up to 12 components. An option is available to select from 10 possible menus using an additional I/O module and BCD switch.

Programming for the system parameters is achieved by the ADW15 keypad, with an option to carry out the operation via communications port from a remote PC or PLC.

Ingredients mix times, weight checks, settle times and tolerance settings are all features of this comprehensive software program. To ensure system integrity, activities are constantly monitored with an Alarm condition being activated where appropriate.

Very simple auto-calibration routines make this an extremely easy system to set up.

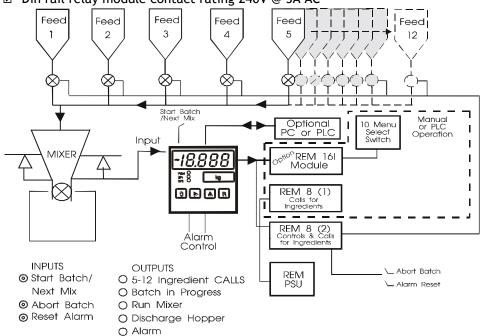
All batch details and weights will be recorded on an optional printer if necessary.

The Batch Weigher is part of a family of special Weighing, Filling and Throughput Control Systems offered by Mantracourt Electronics Limited.

ADW-BW Component Batch Weighing Controller

features

- ☑ Upto 12 Components
- ☑ Inflight compensation for all components
- ☑ Selectable batch totals
- ☑ Manual or PLC operation
- ☑ Password security
- ☑ Din rail relay module contact rating 240V @ 5A AC
- ☑ Optional 10 Menu selection
- ☑ Easy calibration
- ☑ Mixer timing
- ☑ Panel display sealed to IP65
- ☑ Excitation for up to 4 strain gauges



Options	Accessories
Supplies for 110/240 VAC or 12/24 VDC	IF25 Interface Module Connects up to 25 Batch Weighing Controller to one RS232 port
Communications Port PLC or PC	
Printer Drive	
Menu Selection	

Introduction

Designed around the ADW15 Strain gauge Indicator Controller, and the remote set point relay unit.

The batch controller system software makes provision for the mixing of up to 12 components

In 10 possible menus (see options). Programming from the ADW-BW, keypad allows for the control of quantities from each of the feeds, and the number of batches required.

Ingredient mix times, weight checks, and settle times are all features of the comprehensive software control within the ADW-BW.

With the inclusion of interface boards, full remote control can be affected from a PC or PLC, and a printed record of all the required activity can be taken onto a printer.

Specifications

Operating Instructions for Batch Weighing Controller

data, set in EEPROM puts ual trip points = SP - IF)
puts ual trip points = SP - IF)
ial trip points = SP - IF)
must be less than 'CALH'
5, +16 = 10 menu)
nt, set in seconds
as discharged before allowing next
t on call for product. Set in seconds
seconds 1->255 Increase in weight
in weight check time interval. (1It).Set
'RABUS Format'
'address' when the communications port

Batch Controller System Description

The Batch Controller is based upon the strain gauge indicator controller ADW15 and the REM 8 multi set point DIN rail units.

A special software program in the ADW15 makes provision for the mixing of up to 12 components into one mixing vessel.

Each of the components is controlled by values selected under mnemonics entered from the keypad of the ADW-BW.

A BCD switch with REM16I allows for the selection of up to 10 menus. The range of mnemonics include Set Points and In-flight compensation valves which, when programmed set the conditions for a relay to operate, controlling the operation of valves and therefore the amount of component from each feed into the mixer/weigh vessel.

A batch control mnemonic 'bt' provides a batch total which controls the desired number of mixes from the components feeds. This value can be set from 1 to 255 batches.

The components mix time can be set from between 0 to 19999 seconds, by the setting of the mnemonic 'tl', before a discharge is activated.

Auto calibration of the ADW15 controller is achieved by 'low' and 'high' calibration point settings.

Further mnemonics allow for a display averaging and decimal point position, and settle time figure before call of the next component.

ADW-BW Indicator Controller

Calibration Automatic digital by use of keypad and 1 (or 2) known weights. Manual

calibration can also be selected

Sensitivity ± 0.95 to 3.8mV/V for full scale. (Factory set to 2.5mV/V.) User analogue

calibration if required by link change and 15 turn trimmers

Excitation 10V d.c. nominal, 150mA maximum

Compensation By ± sense wire to compensate for cable, connection volt drops and any

variation in 10V supply

Accuracy 90 days \pm 0.08% of reading \pm 0.05% of FSD typical

Drift 0.002%/°C typical @ 2.5mV/V

Display Rate 0.1 seconds for standard update

Input Average Set by keypad, up to 64 standard updates

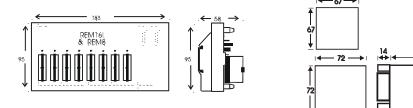
Display 1 x 4.5 digit, High brightness, 10mm Red LED

2 x 3mm LED's for SP1 and SP2 status

1 x 3mm LED for hold

The Relay Output Module

The module consists of 8 relays rated at 240 volts 5 Amps - SPCO, Alarm via 30V 50mA NC contact, DIN rail mounted for a G or top hat profile. Each relay is plugg-able and connections are made by 2.5mm field screw terminals. Indication of relay status is shown by LED's. Trip points volt free contact. The module can be situated up to 2 metres from the ADW strain gauge indicator controller.



Supplement To be read in conjunction with ADW15 user Manual

Set Up Parameters

1 Enter the password to proceed with set up parameters.

2 i) Enter system parameters i.e. 5 or 12 Components under (DA) as follows:-

DA 0 - 7 = 12 components + display averaging
DA 8 -15 = 5 components + display averaging

DA 16 -23 = 12 components + menu select + display averaging
DA 24 - 31 = 5 components + menu select + display averaging

Note: The selection of 5 components reduces the menu size to SP1-5 and IF1-5

ii) Enter required set point values for SP1 to SP12

iii) Enter batch total required (bt)- must be 1 or greater

iv) Enter mixing time in seconds (tL)v) Enter the settle time in seconds (Sttl)

vi) Enter Tolerance settings for mixer hopper empty (tol)
vii) Enter delay time before, increase in weight check (bdt)
viii) Enter increase in weight check timer interval in seconds (IIt)

ix) Enter increase in weight amount (ICA)

Calibration settings CALL and CALH together with auto tare, display, averaging and decimal point selection can be set independently of the controller system as described in the ADW15 user manual.

In Flight values (IF1-IF12) should be determined after running an initial batch.

Hardware Configuration

Relays RL1 to RL8 of REM8 (1) and RL1 to RL4 of REM8 (2) operate the set points SP1 to SP12 (and corresponding in flight IF1 to IF12), as required for the number of components in the mix. Components can be omitted by setting their corresponding SP values to zero.

Relay RL6 of REM2 operates the mix time running.

Relay RL7 of REM2 operates the discharge.

Relay RL8 of REM2 operates the batch in progress.

Procedure

- 1. Start signal from 'reset' terminals on the ADW-BW. (This doubles as start batch and start mix contact).
- 2. The batch in progress relay (RL8) operates, the ADW15 auto tares and calls for the first component. The first set point relay operates (e.g. SP1 = RL1 relay).
- 3. When SP1 is achieved, the relay drops out and after the programmed settle time, the unit auto tares and the next relay operates (e.g. SP2 = RL2 relay).
- 4. When SP2 is achieved, the relay drops out and after the programmed settle time, the unit auto tares and the next relay operates (eg SP3 = RL3 relay).

The sequence is repeated for up to 12 components as required.

If the set point = 0 then that relay is omitted

- 5. On completion of the discharge i.e. the container weight returned to zero, within the tolerance programmed, 'tol' the relay R7 drops out.
- 6. The system will now be ready for a further mix to take place. This is achieved by a further press of the start batch/next mix contact, the unit auto tares and the sequence is repeated.
- 7. On completion of the last mix, the start batch/next mix contact is again pressed to acknowledge that the batch is complete. The batch in progress relay now drops out.

 This completes the batch sequence.

Alarm Conditions

(Defined as contacts open on SP3 via AN+/AN- on the ADW15 rear panel)

- 1. Loss of communications to the REM units will cause the display to flash at a rate of once per second. This is a self cancelling alarm.
- 2. A 'NO' increase in weight as determined by 'IIt and ICA' after the time programmed for 'bdt', will cause an alarm (This alarm will be cancelled if the component reaches its set point value).
- 3. An alarm reset is achieved by a contact closure on input1 of the J4 on the REM8.
- 4. An 'ABORT FUNCTION' function is achieved by a contact closure on input 2 of J4 on the REM8. This will remove all 'CALLS' leaving the ADW-BW waiting to discharge its contents if the ADW-BW, is however, running the mix time, then this time will finish before discharging. On discharge being complete a 'NEXT FILL/START' signal will cancel the batch in progress relay.

Note: i) When a mixing sequence is in operation, it is not possible to enter the menu

ii) The alarm condition is achieved by the SP3 contact board replacing the analogue output connections on the rear of the ADW15

iii) The minimum system hardware requirement is:

1 x ADW-BW

1 x REM8

1 x REM PSU

1 x REM C1 cable

(See option 1. Diagram for details)

Communications to be read in Conjunction with Chapter 7 of the ADW15 User Manual

DEC	HEX	Description	•
1	1	REQUEST ALL VARIABLES	(AS ADW15)
2	2	REQUEST DISPLAY DATA	(AS ADW15)
3	3	INHIBITED RETURN NAK	(rEC)
4	4	UPDATE SET POINT 1	(SP1)
5	5	UPDATE IN-FLIGHT 1	(IF1)
6	6	UPDATE SET POINT 2	(SP2)
7	7	UPDATE IN-FLIGHT 2	(IF2)
8	8	UPDATE SET POINT 3	(SP3)
9	9	UPDATE IN-FLIGHT 3	(IF3)
10	Α	UPDATE SET POINT 4	(SP4)
11	В	UPDATE IN-FLIGHT 4	(IF4)
12	С	UPDATE SET POINT 5	(SP5)
13	D	UPDATE IN-FLIGHT 5	(IF5)
14	Ε	UPDATE SET POINT 6	(SP6)
15	F	UPDATE IN-FLIGHT 6	(IF6)
16	10	UPDATE SET POINT 7	(S7)
17	11	UPDATE IN-FLIGHT 7	(IF7)
18	12	UPDATE SET POINT 8	(SP8)
19	13	UPDATE IN-FLIGHT 8	(IF8)
20	14	UPDATE SET POINT 9	(SP9)
21	15	UPDATE IN-FLIGHT 9	(IF9)
22	16	UPDATE SET POINT 10	(SP10)
23	17	UPDATE IN-FLIGHT 10	(IF10)
24	18	UPDATE SET POINT 11	(SP1)
25	19	UPDATE IN-FLIGHT 11	(IF11)
26	1A	UPDATE SET POINT 12	(SP12)
27	1B	UPDATE IN-FLIGHT 12	(IF12)
28	1C	UPDATE BATCH TOTAL	(bt)
29	1D	UPDATE MIXER TIMER	(t1)
30	1E	INHIBITED. RETURNS A 'NAK'	, ,
31	1F	INHIBITED. RETURNS A 'NAK'	
32	20	INHIBITED. RETURNS A 'NAK'	
33	21	INHIBITED. RETURNS A 'NAK'	
34	22	UPDATE DISPLAY AVERAGES	(DA)
35	23	UPDATE DECIMAL POINT	(DP)
36	24	UPDATE SETTLE TIME	(ST)
37	25	UPDATE TOLERANCE FOR RETURN TO START WEIGHT	(TOL)
38	26	UPDATE BLOWER DELAY TIME	
39	27	INCREASE IN WEIGHT TIMER	(Bdt)
40	28	INCREASE IN NUMBER OF DIGITS	(Ht)
41	29	COMMS PROTOCOL	(ICA)
42	2A	CAN NOT BE WRITTEN TO	(Cp)
43	2B	UPDATE RESOLUTION	(STST)
44	2C	EEPROM ENABLE/DISABLE	(Rs)
45	2D	START BATCH	
46	2E	START NEXT MIX	
47	2F	STOP AT END OF MIX	
48	30	SET ALARM RELAY	
49	31	CLEAR ALARM RELAY	
50	32	ABORT MIX	

Response to Command 1 from ADW

Ryto	, •	
Byte 1	Station number	
2,3	DISPLAY	
4,5	RECIPE	
6,7	SET POINT 1	
8,9	IN FLIGHT 1	
10,11	SET POINT 2	
12,13	IN FLIGHT 2	
14,15	SET POINT 3	
16,17	IN FLIGHT 3	
18,19	SET POINT 4	
20,21	IN FLIGHT 4	
22,23	SET POINT 5	
24,25	IN FLIGHT 5	
26,27	SET POINT 6	
28,29	IN FLIGHT 6	
30,31	SET POINT 7	
32,33	IN FLIGHT 7	
34,35	SET POINT 8	
36,37	IN FLIGHT 8	
38,39	SET POINT 9	
40,41	IN FLIGHT 9	
42,43	SET POINT 10	
44,45	IN FLIGHT 10	
46,47	SET POINT 11	
48,49	IN FLIGHT 11	
50,51	SET POINT 12	
52,53	IN FLIGHT 12	
54,55	BATCH TOTAL	
56,57	MIXER TIMER	
58,59	A/D COUNTS FOR LOW CALIBRATION POINT	
60,61	A/D COUNTS FOR HIGH CALIBRATION POINT	
62,63	DISPLAY FOR LOW CALIBRATION POINT	
64,65	DISPLAY FOR HIGH CALIBRATION POINT	(5.4)
66,67	DISPLAY AVERAGE	(DA)
68,69	DECIMAL POINT	(DP)
70,71	SETTLE TIME	(St) (TOL)
72,73	TOLERANCE FOR RETURN TO START WEIGHT BLOWER DELAY	(BT)
74,75	TIME	
76,77	INCREASE IN WEIGHT TIMER	
78,7	INCREASE IN NUMBER OF DIGITS	
80,81	PROTOCOL	
82,83	SDST	
84,85	RESOLUTION	
86	EEPROM ENABLE/DISABLE FLAG	
87	RELAY STATUS (RELAYS 1-8)	
88	EXOR CHECKSUM OF THE ABOVE DATA	

Response to Command 2

Byte	
1	Station number
2,3	DISPLAY READING
4,5	RESULT OF SP1
6,7	RESULT OF SP2
8,9	RESULT OF SP3
10,11	RESULT OF SP4
12,13	RESULT OF SP5
14,15	RESULT OF SP6
16,17	RESULT OF SP7
18,19	RESULT OF SP8
20,21	RESULT OF SP9
22,23	RESULT OF SP10
24,25	RESULT OF SP11
26,27	RESULT OF SP12
28	ALARM FLAG
29	BATCH COUNT
30, 31	RELAY FLAGS SEE BELOW
32, 33	GROSS
34	CHECKSUM

BW Relay Status Flags

Data Returned from Command 2 Bytes 30 & 31

Description
Ingredient 1 relay call on
Ingredient 2 relay call on
Ingredient 3 relay call on
Ingredient 4 relay call on
Ingredient 5 relay call on
Ingredient 6 relay call on
Ingredient 7 relay call on
Ingredient 8 relay call on
Ingredient 9 relay call on
Ingredient 10 relay call on
Ingredient 11 relay call on
Ingredient 12 relay call on
Ready for next mix signal
Mixer running
Do discharge
Batch in progress

ADW-BW Alarm Status Flags

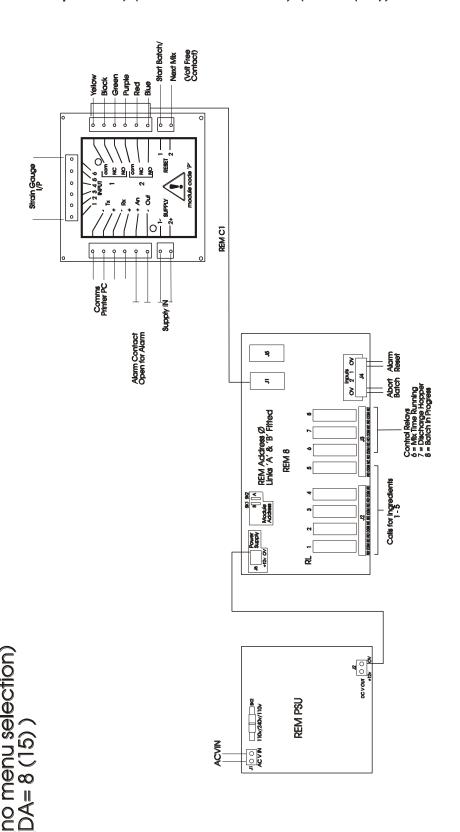
Data Returned from Command 2 Byte 28

Bit Number	Description
1	NOT USED
2	NOT USED
3	NOT USED
4	NOT USED
5	NO 12C BUS DETECTED
6	ALARM SET BY COMMAND 48
7	NO INCREASE IN WEIGHT ALARM
8	NOT USED

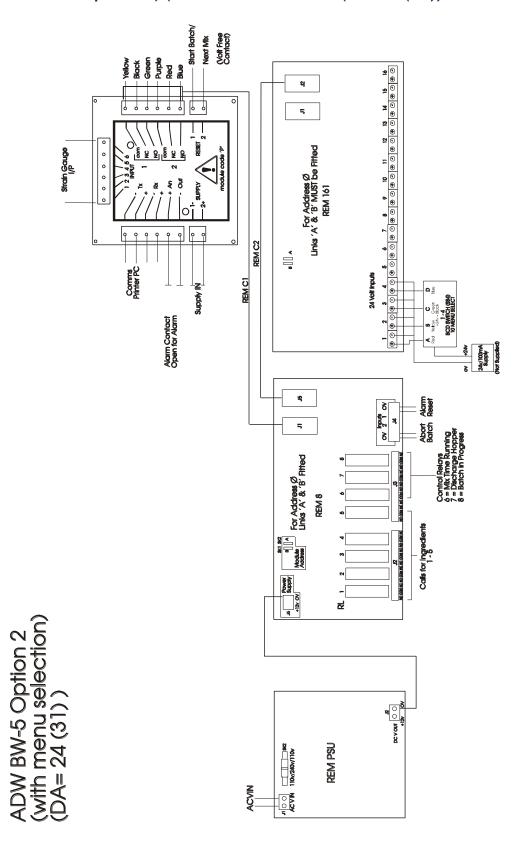
NOTES:

- 1. Batch count is incremented on receipt of "Next mix signal".
- 2. The last mix in the batch requires a "Next mix signal" to clear the batch in progress relay.
- 3. The I2C alarm & no increase in weight alarm are self canceling but may be reset using command 49.
- 4. Recipe REC cannot be updated from the comms. It can only be set by the REM161.

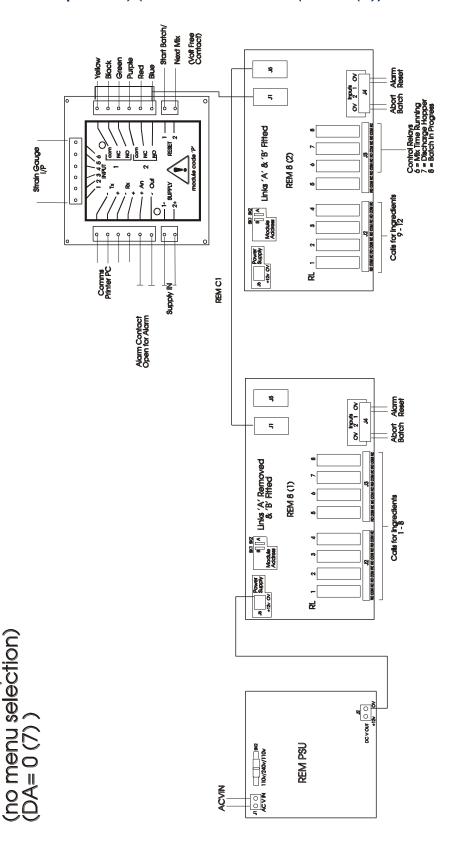
ADW BW Option 1, (no menu selection) (DA=8 (15))



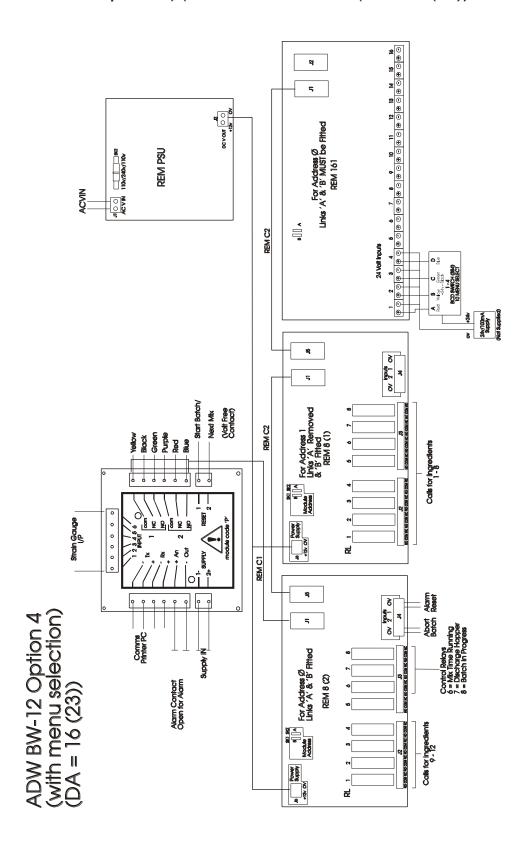
ADW BW Option 2, (with menu selection (DA=24 (31))



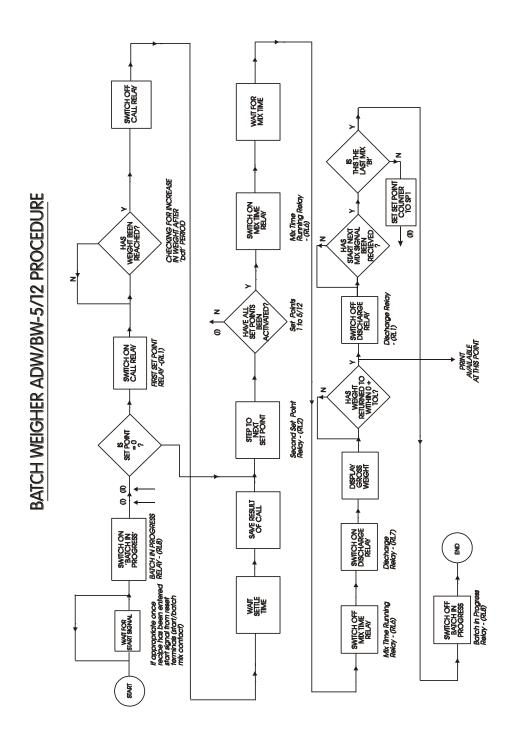
ADW BW Option 3, (no menu selection (DA= 0 (7))



ADW BW Option 4, (with menu selection (DA = 16 (23))



Batch Weigher ADW/BW Procedure



WARRANTY

All ADW products from Mantracourt Electronics Ltd., ('Mantracourt') are warranted against defective material and workmanship for a period of (3) three years from the date of dispatch.

If the 'Mantracourt' product you purchase appears to have a defect in material or workmanship or fails during normal use within the period, please contact your Distributor, who will assist you in resolving the problem. If it is necessary to return the product to 'Mantracourt' please include a note stating name, company, address, phone number and a detailed description of the problem. Also, please indicate if it is a warranty repair.

The sender is responsible for shipping charges, freight insurance and proper packaging to prevent breakage in transit.

'Mantracourt' warranty does not apply to defects resulting from action of the buyer such as mishandling, improper interfacing, operation outside of design limits, improper repair or unauthorised modification.

No other warranties are expressed or implied. 'Mantracourt' specifically disclaims any implied warranties of merchantability or fitness for a specific purpose. The remedies outlined above are the buyer's only remedies. 'Mantracourt' will not be liable for direct, indirect, special, incidental or consequential damages whether based on the contract, tort or other legal theory.

Any corrective maintenance required after the warranty period should be performed by 'Mantracourt' approved personnel only.





In the interests of continued product development, Mantracourt Electronics Limited reserves the right to alter product specifications without prior notice.

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